

QM-HW4

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- 3.1 算符 $\hat{A}$ 是厄米算符的要求是

$$(\psi, \hat{A}\phi) = (\hat{A}\psi, \phi)$$

将 F_+ 带入左式, 由厄米共轭性质 $(\hat{A}\psi, \phi) = (\psi, \hat{A}^\dagger\phi)$, 有

$$\begin{aligned}(\psi, F_+\phi) &= \frac{1}{2}[(\psi, F\phi) + (\psi, F^\dagger\phi)] \\&= \frac{1}{2}[(F^\dagger\psi, \phi) + (F\psi, \phi)] \\&= (F_+\psi, \phi)\end{aligned}$$

同理可证 F_+, F_- 均为厄米算符。另外, 通过简单带入可以证明

$$F = \frac{1}{2}(F + F^\dagger) + i\frac{1}{2i}(F - F^\dagger) = F_+ + iF_-$$

- 3.2

- $\mathbf{l} = \mathbf{r} \times \mathbf{p}$

$$\mathbf{l} = \begin{vmatrix} i & j & k \\ x & y & z \\ p_x & p_y & p_z \end{vmatrix} \Rightarrow \begin{cases} l_x = yp_z - zp_y \\ l_y = zp_x - xp_z \\ l_z = xp_y - yp_x \end{cases}$$

以 l_x 为例, 有

$$l_x^\dagger = (yp_z - zp_y)^\dagger = (p_z^\dagger y^\dagger - p_y^\dagger z^\dagger) = p_z y - p_y z = yp_z - zp_y = l_x$$

同理可证 l_y, l_z 均是厄米的

- $\mathbf{r} \cdot \mathbf{p}$

$$\begin{aligned}(\mathbf{r} \cdot \mathbf{p})^\dagger &= (xp_x + yp_y + zp_z)^\dagger \\&= p_x x + p_y y + p_z z \\&= xp_x + yp_y + zp_z - 3i\hbar \\&= \mathbf{r} \cdot \mathbf{p} - 3i\hbar\end{aligned}$$

因此该算符不是厄米的, 但是可以添加常数 $-1.5i\hbar$ 使之成为厄米的

- $\mathbf{A} = \mathbf{p} \times \mathbf{l}$

$$\begin{aligned}
A_x^\dagger &= (p_y x p_y - p_y y p_x - p_z z p_x + p_z x p_z)^\dagger \\
&= (p_y x p_y - p_x y p_y - p_x z p_z + p_z x p_z)
\end{aligned}$$

由对易关系

$$\begin{aligned}
[p_y y, p_x] &= p_y y p_x - p_x p_y y \\
&= \hbar^2 \left(\frac{\partial}{\partial x} + y \frac{\partial^2}{\partial x \partial y} - \frac{\partial}{\partial x} - y \frac{\partial^2}{\partial y \partial x} \right) \\
&= 0
\end{aligned}$$

同理可证 $[p_z z, p_x] = 0$ ，因此原式化为

$$A_x^\dagger = (p_y x p_y - p_y y p_x - p_z z p_x + p_z x p_z) - 2i\hbar p_x = A_x - 2i\hbar p_x$$

因此该算符不是厄米的，但是可以添加算符 $-i\hbar p$ 使之成为厄米的

• $\mathbf{B} = \mathbf{r} \times \mathbf{l}$

$$\begin{aligned}
B_x^\dagger &= (y l_z - z l_y)^\dagger \\
&= l_z y - l_y z \\
&= y l_z - z l_y - 2i\hbar x \\
&= B_x - 2i\hbar x
\end{aligned}$$

因此该算符不是厄米的，但是可以添加算符 $-i\hbar \mathbf{r}$ 使之成为厄米的

• 3.5

$$\begin{aligned}
\mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) &= \sum_{\gamma} A_{\gamma} (\mathbf{B} \times \mathbf{C})_{\gamma} \\
&= \sum_{\gamma} A_{\gamma} \left(\sum_{\alpha\beta} \epsilon_{\alpha\beta\gamma} B_{\alpha} C_{\beta} \right) \\
&= \sum_{\alpha\beta\gamma} \epsilon_{\alpha\beta\gamma} A_{\alpha} B_{\beta} C_{\gamma} \\
(\mathbf{A} \times \mathbf{B}) \cdot \mathbf{C} &= \sum_{\gamma} (\mathbf{A} \times \mathbf{B})_{\gamma} C_{\gamma} \\
&= \sum_{\gamma} \left(\sum_{\alpha\beta} \epsilon_{\gamma\alpha\beta} A_{\alpha} B_{\beta} \right) C_{\gamma} \\
&= \sum_{\alpha\beta\gamma} \epsilon_{\alpha\beta\gamma} A_{\alpha} B_{\beta} C_{\gamma}
\end{aligned}$$

因此上述二者相等

$$\begin{aligned}
[A \times (B \times C)]_\alpha &= \sum_{\beta\gamma} \epsilon_{\alpha\beta\gamma} A_\beta (B \times C)_\gamma \\
&= \sum_{\beta\gamma} \epsilon_{\alpha\beta\gamma} A_\beta \left(\sum_{ij} \epsilon_{ij\gamma} B_i C_j \right) \\
&= \sum_{\beta\gamma} \sum_{ij} \epsilon_{\alpha\beta\gamma} \epsilon_{ij\gamma} A_\beta B_i C_j \\
&= \sum_{ij\beta} A_\beta B_i C_j \sum_{\gamma} \epsilon_{\alpha\beta\gamma} \epsilon_{ij\gamma} \\
&= \sum_{ij\beta} A_\beta B_i C_j (\delta_{\alpha i} \delta_{\beta j} - \delta_{\alpha j} \delta_{\beta i}) \\
&= \sum_{ij\beta} A_\beta B_i C_j \delta_{\alpha i} \delta_{\beta j} - \sum_{ij\beta} A_\beta B_i C_j \delta_{\alpha j} \delta_{\beta i} \\
&= \sum_{i\beta} A_\beta B_i C_j \delta_{\alpha i} - \sum_{j\beta} A_\beta B_\beta C_j \delta_{\alpha j} \\
&= \sum_{\beta} A_\beta (B_\alpha C_\beta - B_\beta C_\alpha) \\
&= A \cdot (B_\alpha C) - (A \cdot B) C_\alpha
\end{aligned}$$

$$[(A \times B) \times C]_\alpha = A \cdot (B_\alpha C) - A_\alpha (B \cdot C)$$

• 3.6

$$\begin{aligned}
[F, A \cdot B] &= F \sum_i A_i B_i - \sum_i A_i B_i F \\
&= F \sum_i A_i B_i - \sum_i A_i F B_i + \sum_i A_i F B_i - \sum_i A_i B_i F \\
&= [F, A] \cdot B + A \cdot [F, B]
\end{aligned}$$

$$\begin{aligned}
[F, A \times B]_x &= [F, A_y B_z - A_z B_y] \\
&= F A_y B_z - F A_z B_y - A_y B_z F + A_z B_y F \\
&= (F A_y B_z - A_y F B_z - F A_z B_y + A_z F B_y) + (A_y F B_z - A_y B_z F - A_z F B_y + A_z B_y F) \\
&= [F, A] \times B + A \times [F, B]
\end{aligned}$$

• 3.10

(a) 由于 $\frac{1}{r}$ 是厄米的，因此有

$$\begin{aligned}
p_r^\dagger &= \frac{1}{2} \left(\frac{1}{r} \mathbf{r} \cdot \mathbf{p} + \mathbf{p} \cdot \mathbf{r} \frac{1}{r} \right)^\dagger \\
&= \frac{1}{2} \left((p_x x + p_y y + p_z z) \frac{1}{r} + \frac{1}{r} (x p_x + y p_y + z p_z) \right) \\
&= \frac{1}{2} \left(\mathbf{p} \cdot \mathbf{r} \frac{1}{r} + \frac{1}{r} \mathbf{r} \cdot \mathbf{p} \right) \\
&= p_r
\end{aligned}$$

(b)球坐标系中散度表示为

$$\nabla \cdot v = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$$

因此可做如下化简

$$\begin{aligned} p_r \psi &= -\frac{i\hbar}{2} \left(\frac{1}{r} \mathbf{r} \cdot \nabla + \nabla \cdot \mathbf{r} \frac{1}{r} \right) \psi \\ &= -\frac{i\hbar}{2} \left(\frac{\partial \psi}{\partial r} + \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \psi) \right) \\ &= -i\hbar \left(\frac{\partial \psi}{\partial r} + \frac{\psi}{r} \right) \\ \Rightarrow p_r &= -i\hbar \left(\frac{\partial}{\partial r} + \frac{1}{r} \right) \end{aligned}$$

(c)

$$\begin{aligned} [r, p_r] \psi &= (r p_r \psi - p_r r \psi) \\ &= i\hbar \left(-r \frac{\partial \psi}{\partial r} - \psi + \frac{\partial}{\partial r} (r \psi) + \psi \right) \\ &= i\hbar \psi \\ \Rightarrow [r, p_r] &= i\hbar \end{aligned}$$

(d)

$$\begin{aligned} p_r^2 \psi &= -\hbar^2 \left(\frac{\partial}{\partial r} + \frac{1}{r} \right) \left(\frac{\partial \psi}{\partial r} + \frac{\psi}{r} \right) \\ &= -\hbar^2 \left(\frac{\partial^2 \psi}{\partial r^2} + \frac{2}{r} \frac{\partial \psi}{\partial r} \right) \\ \Rightarrow p_r^2 &= -\hbar^2 \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) = -\hbar^2 \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} \end{aligned}$$

(e)已知

$$\begin{aligned} \nabla^2 &= \nabla \cdot (\nabla) = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \\ p^2 &= -\hbar^2 \nabla^2 \\ l^2 &= -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \end{aligned}$$

带入d的结果即可证明

$$p^2 = \frac{1}{r^2} l^2 + p_r^2$$

• 3.12

$$\begin{aligned} [\hat{x}, \hat{H}] &= [\hat{x}, \frac{p^2}{2m}] \\ &= \frac{1}{2m} (p[x, p] + [x, p]p) \\ &= \frac{i\hbar}{m} p \end{aligned}$$

因此动量的平均值转换成位置与哈密顿量的对易表示

$$\begin{aligned} \bar{p} &= \frac{m}{i\hbar} \overline{[\hat{x}, \hat{H}]} \\ &= \frac{m}{i\hbar} \int \psi^* [\hat{x}, \hat{H}] \psi d\epsilon \\ &= \frac{m}{i\hbar} \int E(\psi^* \hat{x} \psi - \psi^* \hat{x} \psi) d\epsilon \\ &= 0 \end{aligned}$$

• 3.14 l_z 的本征态可以表示为

$$\psi_m(\phi) = \frac{1}{\sqrt{2\pi}} e^{im\phi}$$

$$L_z = m\hbar, m = 0, \pm 1, \pm 2, \dots$$

故有

$$\begin{aligned} \bar{l}_z &= \int \psi_m^* l_z \psi_m d\tau \\ &= \frac{m\hbar}{2\pi} \int_0^{2\pi} d\phi \\ &= m\hbar \end{aligned}$$

由对易关系 $[l_z, l_x] = i\hbar l_y$, 有

$$\begin{aligned} \bar{l}_y &= \frac{1}{i\hbar} \overline{[l_z, l_x]} \\ &= \frac{1}{i\hbar} \int \psi_m^* [l_z, l_x] \psi_m d\tau \\ &= \frac{m}{i} \int (\psi_m^* l_x \psi_m - \psi_m^* l_x \psi_m) d\tau \\ &= 0 \end{aligned}$$

同理, $\bar{l}_x = 0$

• 3.16

(a) Y_{lm} 是 $\hat{l}_z$ 的本征态, 本征值为 $m\hbar$, 因此在本题的波函数情形下, l_z 可能测得 $\hbar$ 和 0, 概率分别为 $|c_1^2|$ 和 $|c_2^2|$

(b) Y_{lm} 也是 l^2 的本征态，本征值为 $l(l+1)\hbar^2$ ，本题中可能测得 $2\hbar^2$ 和 $6\hbar^2$ ，概率分别为 $|c_1|^2$ 和 $|c_2|^2$

• 12题

$$\begin{aligned} H\psi &= E\psi \\ \left[\frac{1}{2I_1}(l_x^2 + l_y^2 + \frac{1}{2}l_z^2) + \frac{1}{2I_2}l_z^2 \right] \psi &= E\psi \\ \frac{1}{2I_1}l^2\psi + \frac{2I_1 - I_2}{4I_1I_2}l_z^2\psi &= E\psi \end{aligned}$$

在球坐标系中，两算符的本征函数表示分别如下

$$\begin{cases} l^2 Y_{lm} = l(l+1)\hbar^2 Y_{lm} \\ l_z^2 Y_{lm} = m^2 \hbar^2 Y_{lm} \end{cases}$$

因此能量本征值

$$E = \frac{l(l+1)\hbar^2}{2I_1} + \frac{2I_1 - I_2}{4I_1I_2} m^2 \hbar^2$$

相应的本征函数

$$Y_{lm} = (-1)^m \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\cos\theta) e^{im\phi}$$